

ABSTRACT

According to the manipulator-type robot of the present invention, a manipulator base contains a connection case for making cable connection to an external device. In the connection case, a signal-line connecting section for external connection is disposed on a predetermined signal line of a cable that is routed through the inside of the manipulator. Besides, the connection case contains, other than the aforementioned signal-line connecting section for making connection to outside, an additional signal-line connecting section.